# **EECS 336:** Lecture 8: Introduction to Recall: a flow graph G = (V, E) is a directed graph Algorithms

Network Flow: Ford-fulkerson, duality, minimum cut

**Reading:** 7.0-7.5

Announcements: midterm tuesday

- closed book, closed notes.
- dynamic programming.
- focus:
  - writing Parts I-II.
  - writing Parts III-IV (given Parts I-II.)

### Last Time:

- reduction
- Network flow defn
- Bipartite matching
- reduction: matching  $\Rightarrow$  flow.

### Today:

- Network flow
- duality: max flow = min cut

- c(e) =capacity if edge e.
- $s \in V$  is source.
- $t \in V$  is sink.

**Def:** a flow f in G is an assignment of flow to edges "f(e)" satisfying:

- capacity:  $\forall e, f(e) \leq c(e)$
- conservation:  $\forall v \neq s, t,$

$$\sum_{e \text{ into } v} f(e) = \sum_{e \text{ out of } v} f(e)$$

**Recall:** the **value** of a flow is:

$$|f| = \sum_{e \text{ out of } s} f(e) = \sum_{e \text{ into } t} f(e)$$

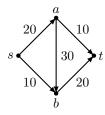
Recall: Max Network Flow Probem

**input:** flow graph  $G, s, t, c(\cdot)$ .

**output:** flow f with maximum value.

## **Network Flow**

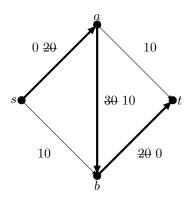
### Example:



Max flow = 30.

**Idea:** repeatedly push flow on s-t paths until can't push anymore.

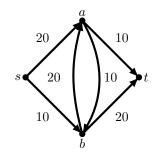
**Example:** Push 20 on P = (s, a, b, t)



**Note:** when pushing flow, we can undo flow already pushed.

**Def:** the residual graph  $G_f$  for flow f on G is the graph that represents capacity constraints for flows after pushing f.

Example:  $G_f$ 



Construction:  $G_f = (V, E_f), c_f(\cdot)$ :

For each  $e = (u, v) \in E$ ,

(if 
$$f(e) = c(e)$$
 discard  $e$ )

• if 
$$f(e) < c(e)$$
,

$$-$$
 add  $e$  to  $E_f$ 

$$-c_f(e) = c(e) - f(e)$$

• if 
$$f(e) > 0$$

$$- \text{ let } e' = (v, u)$$

$$-$$
 add  $e'$  to  $E_f$ 

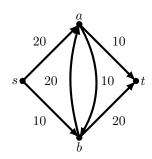
$$-c_f(e') = c(e') + f(e)$$

**Def:** the residual capacity of e in  $E_f$  is  $c_f(e)$ .

**Def:** the <u>bottleneck</u> capacity of s-t path P in  $G_f$  is minimum residual capacity of any edge in P.

**Def:** an <u>augmenting path</u> P in a residual graph  $G_f$  is a path with positive bottleneck capacity.

**Example:**  $G_f$  after pushing 20 on P = (s, a, b, t)



Augmenting path P = (s, b, a, t) with bottleneck capacity 10.

Augment f with flow of 10 on P:

- $f(s,b) \leftarrow f(s,b) + 10$
- $f(a,b) \leftarrow f(a,b) 10$
- $f(a,t) \leftarrow f(a,t) + 10$

Note: can find augmenting paths with BFS.

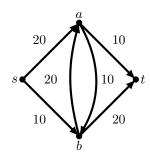
**Algorithm:** Augment f with P

- $b = \text{bottleneck}(P, G_f)$ .
- for e in P:
  - if e a forward edge:

\* 
$$f(e) \leftarrow f(e) + b$$

- if e a back edge:
  - \* let e' = back edge
  - \*  $f(e') \leftarrow f(e) b$ .

**Example:**  $G_f$  after augmenting with P = (s, b, a, t)



No more augmenting paths!

Algorithm: Ford-fulkerson

- $f \leftarrow \text{null flow}$ .
- $G_f \leftarrow G$ .
- while exists s-t path P in  $G_f$  (by BFS)
  - augment f with P.
  - $-G_f \leftarrow \text{residual graph for } G \text{ and } f.$

• return f

### Runtime

Each iteration:

- construct  $G_f: O(m)$ .
- find P: O(m).
- augmentation: O(n).
- (Total: O(m))

**Fact:** the value of flow increases by bottleneck capacity in each iteration.

**Theorem:** if C is upper bound on max flow and all capacities are integral then algorithm terminate in O(C) iterations with runtime O(mC).

**Proof:** (by "measure of progress")

- 1. bottleneck capacities integral:
  - current residual capacities intergal
    - $\Rightarrow$  integral bottleneck capacity
    - $\Rightarrow$  next residual capacities integral
  - induction!
- 2. bottleneck capacities  $\geq 1$
- 3. flow increases by 1 each iteration
- 4. terminate in  $\leq C$  iterations.

Note:  $C \leq \sum_{e \text{ out of } s} c(e)$ .

**Note:** Clever choice of augmenting paths gives runtime  $O(m^2 \log C)$ .

#### Correctness

- 1. f is feasible.
- 2. f is optimal.

**Lemma:** f is feasible.

**Proof:** induction!

## Max flow = min cut

"duality: for maximization problem there is a corresponding minimization problem"

**Recall:** an s-t cut (A, B) is partion of V into A and B with  $s \in A$  and  $t \in B$ .

**Def:** the capacity of cut (A, B) is

$$c(A, B) = \sum_{e \text{ from } A \text{ to } B} c(e)$$

Goal: flow algorithm is optimal

**Proof Approach:** primal = dual.

Claim 1: any flow f and any cut (A, B) then  $|f| \le c(A, B)$ .

value of flow

Claim 2: for flow  $f^*$  with no augmenting path in  $G_{f^*}$  then exists cut  $(A^*, B^*)$  with  $|f^*| = c(A^*, B^*)$ 

#### Picture:

**Proof:** (of theorem)

• all flows

$$|f| \underbrace{\leq}_{\text{by Claim 1}} c(A^*, B^*) \underbrace{=}_{\text{by Claim 2}} |f^*|$$

**Corollary:** value of max flow = capacity of min cut

**Lemma:** for any flow f, cut (A, B) then,  $|f| = \sum_{e \text{ out of } A} f(e) - \sum_{e \text{ into } A} f(e)$ 

**Proof:** (by picture, see text for formal proof)

**Proof:** (of Claim 1)

From Lemma:

$$|f| = \sum_{e \text{ out of } A} f(e) - \sum_{e \text{ into } A} f(e)$$

$$\leq \sum_{e \text{ out of } A} f(e)$$

$$\leq \sum_{e \text{ out of } A} c(e)$$

$$= c(A, B).$$

**Proof:** (of Claim 2) no s-t path in  $G_f$ :

- let  $A^*$  be vertices connected to s.  $> (B^* = V \backslash A^*)$
- $(A^*, B^*)$  is cut: -  $s \in S^*$

 $-t \in B^*$ 

• for all e = (u, v) out of  $A^*$  in G:

$$- e \notin G_f$$
$$\Rightarrow f^*(e) = c(e)$$

• for all e = (u, v) in to  $A^*$  in G:

$$- e' = (v, u) \notin G_f$$
$$\Rightarrow f^*(e) = 0$$

• Lemma

$$\Rightarrow |f| = \sum_{e \text{ out of } A^*} f(e) - \sum_{e \text{ into } A^*} f(e)$$
$$= \sum_{e \text{ out of } A^*} c(e) - 0$$
$$= c(A^*, B^*).$$

#### Summary

- algorithm: augmenting paths in residual graph.
- correctness: max-flow min-cut theorem.
- many problems can be reduced to network flows.
- entire courses on network flows.