

EECS 336: Lecture 4: Introduction to Algorithms

Dynamic Programming (cont)

Reading: 6.4-6.8

Last Time:

- Dynamic Programming (a derivation)
- Weighted interval scheduling

Today:

- Dynamic Programming (a framework)
 - Integer Knapsack
-

Example: Weighted Interval Scheduling

input:

- n jobs $J = \{1, \dots, n\}$
- s_i = start time of job i
- f_i = finish time of job i
- v_i = value of job i

compatibility constraint: Only one job can run at once.

output: Schedule $S \subseteq J$ of compatible jobs with maximum total value.

Iterative DP

Algorithm: iterative weighted interval scheduling

1. initialize array $\text{next}[i]$
sort jobs by increasing start time
 $\text{OPT}[n + 1] = 0$
2. for $i = n$ down to 1:
 $\text{OPT}[i] = \max(v_i + \text{OPT}[\text{next}[i]], \text{OPT}[i + 1]).$
3. return $\text{OPT}[1]$

I. identify subproblem in English

$\text{OPT}(i)$ = “optimal schedule of $\{i, \dots, n\}$ (sorted by starting time)”

II. specify subproblem recurrence (argue correctness)

$\text{OPT}(i) = \max(\text{OPT}(i + 1), v_i + \text{OPT}(\text{next}[i]))$

III. solve the original problem from subproblems

Optimal Interval Schedule = $\text{OPT}(1)$

IV. identify base case

$\text{OPT}(n + 1) = 0$

V. write iterative DP.

VI. runtime analysis.

$O(n) + \text{initialization} = O(n \log n)$

VII. implement in your favorite language (Python!)

Dynamic Programming: Finding Subproblems

"find a first decision you can make which breaks problem into pieces that

- do not interact (across subproblems)
- can be described succinctly."

Example: Integer Knapsack

input:

- n objects $S = \{1, \dots, n\}$
- s_i = size of object i (integer)
- v_i = value of object i
- C = capacity of knapsack (integer)

output:

- subset $K \subseteq S$ of objects that
 - (a) fit in knapsack together
(i.e., $\sum_{i \in K} s_i \leq C$)
 - (b) maximize total value
(i.e., $\sum_{i \in K} v_i$)

Question: What is "first decision we can make" to separate into subproblems?

Answer: Is item 1 in the knapsack or not?

- if 1 in knapsack:
value of knapsack is $v_i +$ optimal knapsack value on $S \setminus \{1\}$ with capacity $C - s_1$.
- if 1 not in knapsack:
value of knapsack is optimal knapsack on $S \setminus \{1\}$ with capacity C .

Succinct description:

- remaining objects $\{j, \dots, n\}$ represented by " j "
- remaining capacity represented by $D \in \{0, \dots, C\}$.

Step I: identify subproblem in English

$\text{OPT}(j, D)$ = "value of optimal size D knapsack on $\{j, \dots, n\}$ "

Step II: write recurrence

$$\text{OPT}(j, D) = \max(\underbrace{v_j + \text{OPT}(j+1, D-s_j)}_{\text{if } s_j \leq D}, \text{OPT}(j+1, D))$$

Justification: either i is in or not (exhaustive.)

Step III: solve original problem

Value of Optimal Knapsack = $\text{OPT}(1, C)$

Step IV: base case

$\text{OPT}(n+1, D) = 0$ (for all D)

Step V: Iterative DP

Algorithm: knapsack

1. $\forall D, \text{OPT}[n+1, D] = 0.$
2. for $i = n$ down to 1,
for $D = C$ down to 0,
 - if i fits (i.e., $s_i \leq D$)

$$\text{OPT}[i, D] = \max[\text{OPT}[j+1, D], v_j + \text{OPT}(j+1, D-s_j)]$$
 - else

$$\text{OPT}[j, D] = \text{OPT}[j+1, D]$$
3. return $\text{OPT}[1, C]$

Step VI: Runtime

$T(m, C) = O(\# \text{ of subprobs} \times \text{cost per subprob}) = O(nC).$

Note: not polynomial time.

Step VII: implementation

(see "guide")

Alternative Approach

“isolate previously made decisions”

Suppose:

- already processed jobs $\{1, \dots, i\}$, and
- used capacity D .

Note: previous decisions succinctly summarized by i and D

Part I: subproblem in english

$\text{OPT}(i, D)$ = "value from remaining knapsack if

- already processed jobs $\{1, \dots, i\}$
- used capacity D ."

Part II: recurrence

$$\text{OPT}(i, D) = \max(\text{OPT}(i + 1, D), \\ \underbrace{v_i + \text{OPT}(i + 1, D + s_i)}_{\text{if } D + s_i \leq C})$$
